## DELFT UNIVERSITY OF TECHNOLOGY

FACULTY OF ELECTRICAL ENGINEERING, MATHEMATICS AND COMPUTER SCIENCE

## TEST NUMERICAL METHODS FOR DIFFERENTIAL EQUATIONS (WI3097 TU) Thursday August 30 2012, 18:30-21:30

1. We consider the following predictor-corrector method for the integration of the initial value problem  $y' = f(t, y), y(t_0) = y_0$ :

$$w_{n+1}^* = w_n + h f(t_n, w_n),$$

$$w_{n+1} = w_n + h \left( (1 - \mu) f(t_n, w_n) + \mu f(t_{n+1}, w_{n+1}^*) \right),$$
(1)

where h,  $\mu$  and  $w_n$  respectively denote the time step, a real number  $(0 \le \mu \le 1)$ , and the numerical solution at time  $t_n$ .

- (a) Show that the local truncation error of the abovementioned method is of order O(h), if  $0 \le \mu \le 1$  and of order  $O(h^2)$ , if  $\mu = \frac{1}{2}$  (Note that this has to be demonstrated for the general differential equation y' = f(t, y)). (3 pt)
- (b) Demonstrate that the amplification factor of the abovementioned method, is given by

$$Q(h\lambda) = 1 + h\lambda + \mu(h\lambda)^{2}.$$
(2 pt)

(c) We consider the following system of non linear differential equations:

$$x_1' = -\sin x_1 + 2x_2 + t, \ x_1(0) = 0, x_2' = x_1 - x_2^2, \ x_2(0) = 1.$$
 (2)

Do one step with the method given in (1) with  $h = \frac{1}{2}$  and  $\mu = \frac{1}{2}$ . (1 pt)

(d) Show that the Jacobian of the right-hand side of (2) at t = 0 is given by:

$$\begin{pmatrix} -1 & 2 \\ 1 & -2 \end{pmatrix}.$$

(1 pt)

(e) Choose  $\mu = 0$ . For which values of h is the method applied to (2) stable at t = 0? Answer the same question for  $\mu = \frac{1}{2}$ .

<sup>&</sup>lt;sup>0</sup>please turn over, For the answers of this test we refer to: http://ta.twi.tudelft.nl/nw/users/vuik/wi3097/tentamen.html

- 2. We approximate the integral  $\int_a^b f(x)dx$  using gridnodes  $x_j = a + (j-1)h$ , where  $x_{n+1} = b$ . For an interval between two adjacent gridnodes,  $(x_j, x_{j+1})$ , the Rectangle Rule gives the approximation  $hf(x_j)$  and a repetitive application gives  $\int_a^b f(x)dx \approx T_0 = h\sum_{j=1}^n f(x_j)$ .
  - a Show that the local truncation error,  $|E_0^I| := |\int_{x_j}^{x_{j+1}} f(x) dx hf(x_j)|$ , and global error,  $|E_0| := |\int_a^b f(x) dx T_0|$  are, respectively, given by

$$|E_0^I| \le \frac{h^2}{2} \max_{x \in [x_j, x_{j+1}]} |f'(x)|, \text{ and } |E_0| \le \frac{(b-a)h}{2} \max_{x \in [a,b]} |f'(x)|.$$
 (3)

Hint: You can use Taylor's Theorem, and  $\max_{x \in [a,b]} |f(x)|$  denotes the maximum of |f(x)| over the interval [a,b]. (2 pt.)

(a) Next we also incorporate the first-order derivative of f in the gridnodes  $\{x_j\}$ . Use Taylor's Theorem to derive that the integral can be approximated by  $T_1$  using the gridnodes with global error  $E_1$ , where

$$\int_{a}^{b} f(x)dx \approx T_{1} = h \sum_{j=1}^{n} \left[ f(x_{j}) + \frac{h}{2} f'(x_{j}) \right], |E_{1}| \leq \frac{(b-a)h^{2}}{6} \max_{x \in [a,b]} |f''(x)|.$$
(4)
(2pt.)

- (b) Use the method from equation (4) with  $h = \frac{1}{2}$  to approximate  $\int_0^1 x^2 dx$  and compare the error with the estimate for  $|E_1|$ . (2pt.)
  - d Next we use the derivatives of f up to the order 2. Further,  $T_2$  and  $E_2$  are, respectively, the approximation of  $\int_a^b f(x)dx$  using these derivatives and the corresponding global error. Show that

$$T_2 = T_1 + \frac{h^3}{3!} \sum_{j=1}^n f''(x_j)$$
, and  $|E_2| \le \frac{(b-a)h^3}{4!} \max_{x \in [a,b]} |f'''(x)|$ . (5)

(2pt.)

(c) Suppose that all values of f and their derivatives contain a error of measurement or rounding, i.e.  $|\tilde{f}^{(k)}(x_j) - f^{(k)}(x_j)| \leq \varepsilon$ , for all j and k-th derivatives (k = 0 gives f itself). Let  $T_2$  and  $\tilde{T}_2$ , respectively, be computed using the exact (f) and available values  $(\tilde{f})$  of f and its derivatives, show that the influence of the this error can be estimated by:

$$|\tilde{T}_2 - T_2| \le (b - a)\varepsilon \left(1 + \frac{h}{2} + \frac{h^2}{3!}\right). \tag{6}$$

(2pt.)