

**ANSWERS OF THE TEST NUMERICAL METHODS FOR  
 DIFFERENTIAL EQUATIONS (WI3097 TU)**

**Tuesday 31 January 2006, 14:00-17:00**

1. a) In (1), substitute  $u^*$  into the second equation, replace  $u_n$  by the exact solution  $y_n$ , and expand

$$\overline{u_{n+1}} = y_n + \beta h f(t_n + \alpha h, y_n + \alpha h f(t_n, y_n))$$

into a Taylorseries:

$$\begin{aligned} \overline{u_{n+1}} &= y(t_n) + \beta h [f + \alpha h f_t + \alpha h f f_y + O(h^2)](t_n, y_n) \\ &= y(t_n) + \beta h f(t_n, y_n) + \alpha \beta h^2 [f_t + f f_y](t_n, y_n) + O(h^3) \\ &= y(t_n) + \beta h y'(t_n) + \alpha \beta h^2 y''(t_n) + O(h^3), \end{aligned}$$

where  $y'' = f_t + f f_y$  (an identity which follows by differentiation of the differential equation  $y' = f(t, y)$ ) has been used to obtain the last line. Now subtracting the expansion  $y(t_{n+1}) = y(t_n) + h y'(t_n) + \frac{h^2}{2} y''(t_n) + O(h^3)$  and dividing by  $h$  gives the expansion of the local truncation error  $\tau_{n+1}$ :

$$\tau_{n+1} = \frac{y(t_{n+1}) - \overline{u_{n+1}}}{h} = (1 - \beta) y(t_n) + \left(\frac{1}{2} - \alpha \beta\right) h y''(t_n) + O(h^2).$$

It follows that  $\tau_{n+1}$  is  $O(1)$  unless  $\beta=1$  and, furthermore, that  $\alpha$  has to be chosen  $\frac{1}{2}$  in order to achieve  $\tau_{n+1} = O(h^2)$ .

- b) Substitute the test equation  $y' = \lambda y$  into (1) with  $\beta=1$ :

$$\begin{aligned} u^* &= u_n + \alpha h \lambda u_n = (1 + \alpha h \lambda) u_n \\ u_{n+1} &= u_n + h \lambda (1 + \alpha h \lambda) u_n = (1 + h \lambda + \alpha (h \lambda)^2) u_n. \end{aligned}$$

It follows that the amplification factor is  $C(h\lambda) = 1 + h\lambda + \alpha(h\lambda)^2$ .

- c) The eigenvalues of the system follow by putting the characteristic polynomial

$$\det \begin{pmatrix} -\lambda & 1 \\ -1 & -\lambda \end{pmatrix} = \lambda^2 + 1$$

equal to zero. This yields the two purely imaginary eigenvalues  $\pm i$ . Substitution of these eigenvalues into the amplification factor of b) gives  $C(h\lambda) = 1 \pm ih - \alpha h^2$ . For stability, the modulus of  $C(h\lambda)$  should be smaller than 1:

$$(1 - \alpha h^2)^2 + h^2 < 1,$$

and thus

$$1 - 2\alpha h^2 + \alpha^2 h^4 + h^2 < 1.$$

This can be reduced to

$$-2\alpha + \alpha^2 h^2 + 1 < 0,$$

and rewritten as the stability condition

$$h^2 < \frac{2\alpha - 1}{\alpha^2}.$$

It follows that no stable stepsizes exist for  $\alpha < \frac{1}{2}$ .

- d) Putting  $x_1 = y$  en  $x_2 = y'$ , we have  $x'_1 = x_2$ , while substitution of the new names into  $y'' + 6y' + 5y = \sin t$  gives  $x'_2 + 6x_2 + 36x_1 = \sin t$ . In vector form:

$$\mathbf{x}' = \begin{pmatrix} 0 & 1 \\ -36 & -6 \end{pmatrix} \mathbf{x} + \begin{pmatrix} 0 \\ \sin t \end{pmatrix}. \quad (1)$$

Now put

$$\det \begin{pmatrix} -\lambda & 1 \\ -36 & -6 - \lambda \end{pmatrix} = \lambda^2 + 6\lambda + 36 = (\lambda + 3)^2 + 27$$

equal to zero and it follows that  $-3 \pm 3i\sqrt{3}$  are the eigenvalues of the system (1).

- e) Putting  $\beta=1$  and  $\alpha = 0$  in (1) we recover the forward Euler method with the stability region as given in the hint of part e) of the assignment. Now mark the eigenvalues in the complex  $h\lambda$ -domain. A rough estimate then shows that a stepsize of  $\frac{1}{10}$  is sufficiently small to bring  $h\lambda$  into the Euler stability region. The precise upperbound for  $h$  ( $\frac{1}{6}$ ) is somewhat larger than 0.1.

2. (a) The exact answer is 0.75. The composite Trapezoidal rule is given by

$$\frac{1}{2} \cdot \left\{ \frac{1}{2} \cdot (1 - 0^3) + 1 - \left(\frac{1}{2}\right)^3 + \frac{1}{2} \cdot (1 - 1^3) \right\} = \frac{11}{16} = 0.6875.$$

The difference with the exact answer is 0.0625.

- (b) The rounding error is less than

$$h \cdot \left\{ \frac{1}{2}\epsilon + \epsilon \dots + \epsilon + \frac{1}{2}\epsilon \right\} \leq n \cdot h \cdot \epsilon = (b - a) \cdot \epsilon.$$

- (c) The Taylor polynomial is given by

$$P_1(x) = f(a) + (x - a)f'(a)$$

whereas the truncation error is:

$$f(x) - P_1(x) = \frac{(x - a)^2}{2} f''(\xi), \text{ with } \xi \in [a, b].$$

(d) Integrating this formula gives:

$$\int_a^b P_1(x)dx = \int_a^b f(a) + (x-a)f'(a)dx = (b-a)f(a) + \frac{(b-a)^2}{2}f'(a).$$

Suppose that  $M_2 = \max_{\xi \in [a,b]} |f''(\xi)|$ . This implies that  $|f(x) - P_1(x)| \leq \frac{(x-a)^2}{2}M_2$ . Integrating this formula gives:

$$\left| \int_a^b f(x)dx - \left( (b-a)f(a) + \frac{(b-a)^2}{2}f'(a) \right) \right| \leq \int_a^b |f(x) - P_1(x)|dx \leq \int_a^b \frac{(x-a)^2}{2}M_2dx = \frac{(b-a)^3}{6}M_2$$

(e) The composite rule is:

$$h \cdot \left\{ f(a) + \frac{h}{2}f'(a) + f(a+h) + \frac{h}{2}f'(a+h) \dots + f(b-h) + \frac{h}{2}f'(b-h) \right\}.$$

The result with the composite rule is:

$$\frac{1}{2} \cdot \left\{ (1-0^3) - 3 \cdot \frac{1}{2} \cdot \frac{1}{2} \cdot 0^2 + (1 - (\frac{1}{2})^3) - 3 \cdot \frac{1}{2} \cdot \frac{1}{2} \cdot (\frac{1}{2})^2 \right\} = \frac{27}{32} = 0.8438.$$

The difference with the exact answer is 0.0938.

(f) For the comparison we note that

- the new method has a worse behavior with respect to rounding errors, because rounding errors of  $f'$  also play a role.
- the new method costs  $n$  function evaluations (of  $f'$ ) more than the Trapezoidal rule
- The truncation error of the new method is given by

$$\frac{n \cdot h^3}{6} \max_{\xi \in [a,b]} |f''(\xi)| = \frac{(b-a)h^2}{6} \max_{\xi \in [a,b]} |f''(\xi)|$$

which is 2 times as large as the truncation error of the Trapezoidal rule.

Conclusion: the new method is worse than the Trapezoidal rule.