

# Method of Characteristics

In Boyce & DiPrima only some (very special) second order partial differential equations are considered. Also first order PDE's do pop up, and we will consider some examples of linear equations.

**Simplest example** 
$$\frac{\partial w}{\partial t} + c \cdot \frac{\partial w}{\partial x} = 0$$

Question: find all solutions  $w = w(x, t)$  of this equation.

Idea: consider the rate of change of  $w$  following a 'moving observer', i.e.  $x = x(t)$ .

applying the chain rule: 
$$\frac{d}{dt} (w(x(t), t)) = \frac{\partial w}{\partial x} \frac{dx}{dt} + \frac{\partial w}{\partial t}$$

If the 'observer' moves with a constant velocity  $c$ :  $\frac{dx}{dt} = c$ .

then it follows from  $\frac{\partial w}{\partial t} + c \frac{\partial w}{\partial x} = 0$  that  $\frac{d}{dt} (w(x(t), t)) = 0$ , so  $w$  is constant for an observer that moves with a velocity  $c$ .

Put otherwise:

$w$  is **constant** along the curves (in this cases straight lines)  $x - ct = x_0$ .

These curves are called the **characteristics** of the solution.

The 'general solution' is then given by  $w(x, t) = P(x - ct)$ , where  $P$  is an arbitrary (differentiable) function of one variable.

If  $w$  is given on a curve that intersects each characteristic in one point, then  $w(x, t)$  is uniquely determined for any point  $(x, t)$ .

Usually this curve is the line  $t = 0$ , in which case one speaks of an **initial condition**. Specifically, if  $w$  has to satisfy  $w(x, 0) = g(x)$

then  $P$  is specified by the constraint  $w(x, 0) = P(x - c \cdot 0) = P(x) = g(x)$ , and the solution becomes  $w = g(x - ct)$ .

Another way to view this: the characteristic going through the 'general' point  $(x, t)$  intersects the axis  $t = 0$  in the point  $(x - ct, 0)$ , so  $w(x, t) = w(x - ct, 0) = g(x - ct)$

**Slightly more general** 
$$\frac{\partial w}{\partial t} + c(x, t) \cdot \frac{\partial w}{\partial x} = 0$$

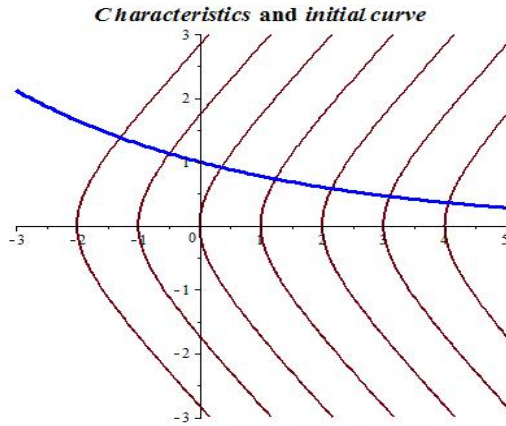
Again we follow the solution  $w = w(x, t)$  along curves  $x = x(t)$  satisfying  $\frac{dx}{dt} = c(x, t)$ , which like before are called the **characteristic curves**.

Along these characteristic curves the solutions  $w = w(x, t) = w(x(t), t)$  are constant.

Often the description of the characteristics can only be given implicitly, say as  $\kappa(x, t) = C$  in that case  $w(x, t) = P(\kappa(x, t))$  satisfies the PDE for any (differentiable) function  $P$ .

The solution of the initial value problem 
$$\begin{cases} \frac{\partial w}{\partial t} + c(x, t) \cdot \frac{\partial w}{\partial x} = 0 \\ w(x, 0) = g(x) \end{cases}$$

can be found explicitly only if it is possible to find the intersection  $(x_0, 0)$  of the characteristic curve through the point  $(x, t)$  and the line  $t = 0$ .



**Example 1**  $x \frac{\partial w}{\partial t} + t \frac{\partial w}{\partial x} = 0$ ,  $w(x, 0) = g(x)$ , for  $x > 0$ .

The PDE can be rewritten as  $\frac{\partial w}{\partial t} + \frac{t}{x} \frac{\partial w}{\partial x} = 0$ .

For the characteristics we have to solve  $\frac{dx}{dt} = \frac{t}{x}$ , which is a separable differential equation:

$$\frac{dx}{dt} = \frac{t}{x} \Rightarrow x dx = t dt \Rightarrow \int x dx = \int t dt \Rightarrow \frac{1}{2}x^2 = \frac{1}{2}t^2 + C$$

The implicit form of the characteristics:  $x^2 - t^2 = K$ .

This gives the general solution  $w(x, t) = P(x^2 - t^2)$ .

To satisfy the initial condition:  $w(x, 0) = P(x^2) = g(x)$ , so  $P(x) = g(\sqrt{x})$ .

It can be easily checked that  $w(x, t) = g(\sqrt{x^2 - t^2})$  indeed satisfies both PDE and initial condition.

**Example 2**  $(3x^2 + 3) \frac{\partial w}{\partial t} + 6t \frac{\partial w}{\partial x} = 0$ .

Again the characteristics are the solutions of a separable DE:

$$\frac{dx}{dt} = \frac{6t}{3x^2 + 3} \Rightarrow (3x^2 + 3) dx = 6t dt \Rightarrow x^3 + 3x = 3t^2 + C$$

So the characteristics are implicitly given by  $\kappa(x, t) = x^3 + 3x - 3t^2 = C$ , and the ‘general solution’ becomes  $w(x, t) = P(x^3 + 3x - 3t^2 - c)$ . In this case it is not possible to find explicitly the solution that satisfies the initial condition  $w(x, 0) = g(x)$ .

## Applications

A first order PDE often pops up as a **continuity equation**

Suppose some density (e.g. water, pollution, cars) is transported over a line (pipe, canal, highway). Let  $\rho = \rho(x, t)$  be the density at position  $x$  at time  $t$  and  $v = v(x, t)$  the velocity. Sometimes the ‘flow’  $q = q(x, t)$ , i.e. the ‘mass’ transported per time unit is introduced:  $q(x, t) = \rho(x, t)v(x, t)$ . The total mass in some interval  $a \leq x \leq b$  at some specific time  $t$  equals

$$m = \int_a^b \rho(x, t) dx$$

Likewise the inflow at  $a$  minus the outflow at  $b$  during a small interval  $\Delta t$  equals

$$m_{in} - m_{out} = (q(a, t) - q(b, t)) \Delta t$$

If there are no ‘sources’ and no ‘sinks’ in the interval (i.e. no mass is created or annihilated) then the change of mass  $dm/dt$  is only due to this in- and outflow, which gives

$$\frac{dm}{dt} = \frac{d}{dt} \left[ \int_a^b \rho(x, t) dx \right] = q(a, t) - q(b, t)$$

which can be rewritten as

$$\int_a^b \frac{\partial \rho}{\partial t}(x, t) dx = q(a, t) - q(b, t) = - \int_a^b \frac{\partial q}{\partial x}(x, t) dx$$

Since this equality holds on any small interval it may be concluded that

$$\frac{\partial \rho}{\partial t} = - \frac{\partial q}{\partial x} = - \frac{\partial(\rho v)}{\partial x} = -\rho \frac{\partial v}{\partial x} - v \frac{\partial \rho}{\partial x} \quad (*)$$

If some further assumptions are made with respect to the relation between flow and densities, like  $q = g(\rho)$ , a PDE for  $\rho$  results:

$$\frac{\partial \rho}{\partial t} = - \frac{\partial g(\rho)}{\partial x} = -g'(\rho) \frac{\partial \rho}{\partial x} \implies \frac{\partial \rho}{\partial t} + g'(\rho) \frac{\partial \rho}{\partial x} = 0$$

This equation is equivalent to the PDE we considered above.

In the theory of flow equations, I came across equation (\*) disguised as

$$-\rho_w \frac{\partial q_x}{\partial x} - q_x \frac{\partial \rho_w}{\partial x} = \rho_w S_s \frac{\partial h}{\partial t}$$

where  $\rho_w$  is the density of water,  $q_x$  the flow in the  $x$ -direction,  $S_s$  the ‘specific storage’, and  $h$  the ‘head’.

If it is further assumed that  $\rho_w \frac{\partial q_x}{\partial x} \gg q_x \frac{\partial \rho_w}{\partial x}$ , which often seems to be the case, the equation reduces to

$$-\frac{\partial q_x}{\partial x} = S_s \frac{\partial h}{\partial t}$$

Plugging in Darcy’s law  $\left( \frac{\partial q_x}{\partial x} = -K_x \frac{\partial h}{\partial x} \right)$  yields a second order PDE for the head:

$$\frac{\partial}{\partial x} \left[ K_x \frac{\partial h}{\partial x} \right] = S_s \frac{\partial h}{\partial t}$$

where  $K_x$  denotes the ‘conductivity’ in the  $x$ -direction.

This equation generalizes to two and three dimensions:

$$\frac{\partial}{\partial x} \left( K_x \frac{\partial h}{\partial x} \right) + \frac{\partial}{\partial y} \left( K_y \frac{\partial h}{\partial y} \right) + \frac{\partial}{\partial z} \left( K_z \frac{\partial h}{\partial z} \right) = S_s \frac{\partial h}{\partial t}$$

which in the case of homogeneous ( $K_x, K_y, K_z$  are constant) anisotropic ( $K_x = K_y = K_z$ ) flow simplifies to

$$K \left( \frac{\partial^2 h}{\partial x^2} + \frac{\partial^2 h}{\partial y^2} + \frac{\partial^2 h}{\partial z^2} \right) = K \nabla^2 h = S_s \frac{\partial h}{\partial t}$$

## Concluding remarks

In fact the second ‘slightly general’ example could be called a linear, homogeneous first order PDE, the general linear first order PDE would then be

$$a(x, t) \frac{\partial w}{\partial t} + b(x, t) \cdot \frac{\partial w}{\partial x} = c(x, t)$$

Like in the case of linear ODE’s it is not difficult to show that the general solution can be split into a homogeneous and a ‘particular’ part:  $w(x, t) = w_H(x, t) + w_P(x, t)$ .

The method of characteristics is also more or less applicable for the so-called *quasi-linear* PDE

$$a(x, t, w) \frac{\partial w}{\partial t} + b(x, t, w) \cdot \frac{\partial w}{\partial x} = c(x, t, w)$$

In both cases explicit solutions can seldom be found.

We will not pursue these extensions further.

## Exercises Method of Characteristics

1. Solve the PDE  $(1+t^2)\frac{\partial u}{\partial t} + 2xt\frac{\partial u}{\partial x} = 0$  with the BC  $u(x,0) = b(x)$ .
2. Solve the PDE  $\frac{\partial u}{\partial t} + e^{-x}\frac{\partial u}{\partial x} = 0$  with the BC  $u(x,0) = b(x)$ .
3. Solve the PDE  $u_t + 2xtu_x = 0$  with the BC  $u(x,0) = b(x)$ .
4. Show that the solution of the general first order linear PDE

$$a(x,t)\frac{\partial w}{\partial t} + b(x,t) \cdot \frac{\partial w}{\partial x} = c(x,t)$$

can be written as  $w(x,t) = w_H(x,t) + w_P(x,t)$ , where  $w_H(x,t)$  satisfies the homogeneous equation

$$a(x,t)\frac{\partial w}{\partial t} + b(x,t) \cdot \frac{\partial w}{\partial x} = 0$$

5. Use the observation of the above exercise to solve the boundary value problem

$$x\frac{\partial u}{\partial x} + y\frac{\partial u}{\partial y} = x, \quad u(1,y) = y^2$$

(A particular solution is easy to 'guess'.)

6. Find the general solution of the linear PDV

$$2\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = g(x)$$

7. Find the general solution of the linear PDV

$$2\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = g(x+y)$$

Hint: the substitution  $\begin{cases} s = x \\ t = x + y \end{cases}$  will bring the equation in the form of the previous exercise.

## Solutions to the exercises

1. Solve the PDE  $(1+t^2)\frac{\partial u}{\partial t} + 2xt\frac{\partial u}{\partial x} = 0$  with the BC  $u(x,0) = b(x)$ .

Solution:

The characteristics follow from  $(1+t^2) dx = 2xt dt$ , which is separable:

$$\frac{dx}{x} = \frac{2t dt}{1+t^2} \Leftrightarrow \int \frac{dx}{x} = \int \frac{2t dt}{1+t^2} \Leftrightarrow \ln|x| = \ln(1+t^2) + K \Leftrightarrow \frac{x}{1+t^2} = c$$

The characteristics are given by  $\frac{x}{1+t^2} = c$ , so the general solution becomes  $u(x,t) = P(x/(1+t^2))$ .

To satisfy the boundary condition:  $u(x,0) = P(x/(1+0^2)) = P(x) = b(x)$ , which gives the solution  $u(x,t) = b\left(\frac{x}{1+t^2}\right)$

2. Solve the PDE  $\frac{\partial u}{\partial t} + e^{-x}\frac{\partial u}{\partial x} = 0$  with the BC  $u(x,0) = b(x)$ .

Solution:

The characteristics follow from  $dx = e^{-x} dt$ , which is separable:

$$e^x dx = dt \Leftrightarrow \int e^x dx = \int dt \Leftrightarrow e^x = t + K \Leftrightarrow e^x - t = K$$

The characteristics are given by  $e^x - t = c$ , so the general solution becomes  $u(x,t) = P(e^x - t)$ .

To satisfy the boundary condition:  $u(x,0) = P(e^x - 0) = P(e^x) = b(x)$ . So  $P(x) = P(e^{\ln x}) = b(\ln x)$ , which gives the solution  $u(x,t) = P(e^x - t) = b(\ln(e^x - t))$ .

It is readily checked that this  $u(x,t)$  indeed satisfies both PDE and BC.

3. Solve the PDE  $u_t + 2xt u_x = 0$  with the BC  $u(x,0) = b(x)$ .

Solution:

The characteristics follow from  $dx = 2xt dt$ , which is separable:

$$\frac{dx}{x} = 2t dt \Leftrightarrow \ln|x| = t^2 + C \Leftrightarrow |x| = e^{t^2+C} = Ke^{t^2} \Leftrightarrow xe^{-t^2} = K$$

The characteristics are given by  $xe^{-t^2} = K$ , so the general solution becomes  $u(t,x) = P(xe^{-t^2})$ , for an arbitrary function  $P$ .

To satisfy the boundary condition:  $u(0,x) = P(xe^0) = P(x) = b(x)$ . So  $P(x) = b(x)$ , which gives the solution  $u(t,x) = P(xe^{-t^2}) = b(xe^{-t^2})$ .

OR: on the characteristics  $u(t, x) = u(t, Ke^{t^2}) = c$ ,  
 so to satisfy  $u(0, x) = b(x)$ :  $u(0, Ke^0) = u(0, K) = b(K)$ .  
 So  $u(t, Ke^{t^2}) = b(K)$ , and in a 'general' point  $(t, x)$ :  
 the solution becomes  $u(x, t) = u(t, (xe^{-t^2})e^{t^2}) = b(xe^{t^2})$ .

4. Show that the solution of the general first order linear PDE

$$a(x, t) \frac{\partial w}{\partial t} + b(x, t) \cdot \frac{\partial w}{\partial x} = c(x, t)$$

can be written as  $w(x, t) = w_H(x, t) + w_P(x, t)$ , where  $w_H(x, t)$  satisfies the homogeneous equation

$$a(x, t) \frac{\partial w}{\partial t} + b(x, t) \cdot \frac{\partial w}{\partial x} = 0$$

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