

$$A(D) = \int_0^1 e^x dx = [e^x]_0^1 = e - 1.$$

b) formules voor het massamiddelpunt (\bar{x}, \bar{y}) .

$$\bar{x} = \frac{1}{m} \iint_D x \rho dA, \quad \bar{y} = \frac{1}{m} \iint_D y \rho dA.$$

$$m = \iint_D \rho dA = \rho \iint_D dA = \rho A(D) = \rho(e-1).$$

$$\bar{x} = \frac{\rho}{m} \int_0^1 \int_0^{e^x} x dy dx = \frac{\rho}{\rho(e-1)} \int_0^1 x e^x dx =$$

$$\frac{1}{e-1} [x e^x - e^x]_0^1 = \frac{1}{e-1}.$$

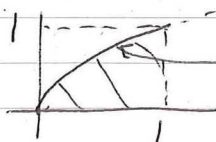
$$\bar{y} = \frac{\rho}{m} \int_0^1 \int_0^{e^x} y dy dx = \frac{1}{e-1} \int_0^1 \left[\frac{1}{2} y^2 \right]_0^{e^x} dx =$$

$$\frac{1}{e-1} \int_0^1 \frac{1}{2} e^{2x} dx = \frac{1}{e-1} \left[\frac{1}{4} e^{2x} \right]_0^1 = \frac{1}{4} \frac{e^2 - 1}{e-1} = \frac{1}{4} (e+1)$$

2.

$$y^2 \leq x \leq 1$$

$$0 \leq y \leq 1$$



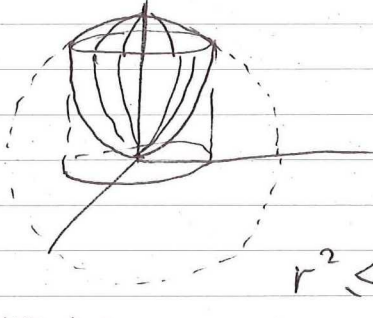
$$x = y^2 \quad y = \sqrt{x} \quad 0 \leq y \leq \sqrt{x}$$

$$0 \leq x \leq 1$$

$$\int_0^1 \int_{y^2}^1 \frac{2y}{x^2+1} dx dy = \int_0^1 \int_0^{\sqrt{x}} \frac{2y}{x^2+1} dy dx = \int_0^1 \frac{1}{x^2+1} [y^2]_0^{\sqrt{x}} dx$$

$$= \int_0^1 \frac{x}{x^2+1} dx = \left[\frac{1}{2} \ln(x^2+1) \right]_0^1 = \frac{1}{2} \ln 2$$

3.



paraboloïde: $z = x^2 + y^2$ $z = r^2$

bol: $x^2 + y^2 + z^2 = 6$ $r^2 + z^2 = 6$

$$z = \sqrt{6 - r^2}$$

$$r^2 \leq z \leq \sqrt{6 - r^2},$$

grenzen van r ;

r is maximaal op de doorsnede van de paraboloïde en de bol.

$$z = r^2 \text{ en } z^2 + r^2 = 6 \text{ dus } r^4 + r^2 = 6$$

$$r^4 + r^2 - 6 = 0$$

$$(r^2 + 3)(r^2 - 2) = 0$$

$$r^2 = 2$$

$$r = \sqrt{2}$$

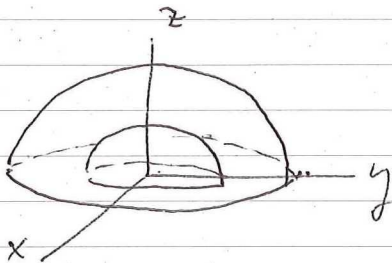
$$0 \leq r \leq \sqrt{2}$$

grenzen θ :

$$0 \leq \theta \leq 2\pi$$

$$\iiint_H f(x, y, z) dV = \int_{\theta=0}^{2\pi} \int_{r=0}^{\sqrt{2}} \int_{z=r^2}^{\sqrt{6-r^2}} f(r \cos \theta, r \sin \theta, z) r dz dr d\theta$$

4.



$$\begin{cases} 1 \leq \rho \leq 2 \\ 0 \leq \varphi \leq \frac{\pi}{2} \\ 0 \leq \theta \leq 2\pi \end{cases}$$

$$\iiint_E \frac{z}{\sqrt{x^2 + y^2 + z^2}} dV =$$

$$\int_{\theta=0}^{2\pi} \int_{\varphi=0}^{\frac{\pi}{2}} \int_{\rho=1}^2 \frac{\rho \cos \varphi}{\rho} \rho^2 \sin \varphi d\rho d\varphi d\theta =$$

$$2\pi \int_{\frac{\pi}{2}}^{\pi} \cos \varphi \sin \varphi \left[\frac{1}{3} \rho^3 \right]_1^2 d\varphi =$$

$$\pi \left[\sin^2 \varphi \right]_0^{\frac{\pi}{2}} \cdot \frac{7}{3} = \frac{7}{3} \pi.$$

5. paramétriser C : $\underline{r}(t) = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} + t \left\{ \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \right\}$

$$\underline{r}(t) = \begin{pmatrix} 1-t \\ 1+t \\ -2+3t \end{pmatrix} \quad 0 \leq t \leq 1$$

$$\underline{r}'(t) = \begin{pmatrix} -1 \\ 1 \\ 3 \end{pmatrix}, \quad \underline{F}(\underline{r}(t)) = \begin{pmatrix} 1-t^2 \\ 3t \\ 3-t \end{pmatrix}.$$

$$\int_C \underline{F} \cdot d\underline{r} = \int_0^1 \underline{F} \cdot \underline{r}'(t) dt =$$

$$\int_0^1 \begin{pmatrix} 1-t^2 \\ 3t \\ 3-t \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 1 \\ 3 \end{pmatrix} dt = \int_0^1 (-(1-t^2) + 3t + 3(3-t)) dt$$

$$\int_0^1 (t^2 + 8) dt = \left[\frac{1}{3} t^3 + 8t \right]_0^1 = 8\frac{1}{3} = \frac{25}{3}$$

2. alternatief (zonder verandering integratievolgorde)

$$\begin{aligned}
 \int_0^1 \int_{y^2}^1 \frac{2y}{x^2+1} dx dy &= \int_0^1 2y [\arctan x]_{y^2}^1 dy = \\
 \int_0^1 2y (\arctan 1 - \arctan y^2) dy &= \\
 \left[\frac{\pi}{4} y^2 \right]_0^1 - \int_0^1 2y \arctan y^2 dy &= \frac{\pi}{4} - \int_0^1 \arctan t dt \\
 &= \frac{\pi}{4} - [t \arctan t]_0^1 + \int_0^1 \frac{t}{1+t^2} dt = \\
 \frac{\pi}{4} - \frac{\pi}{4} + \frac{1}{2} [\ln(1+t^2)]_0^1 &= \frac{1}{2} \ln 2.
 \end{aligned}$$

4. alternatief (met cilinder coördinaten).

$$\begin{aligned}
 \int_{\theta=0}^{2\pi} \int_{r=0}^1 \int_{z=\sqrt{1-r^2}}^{\sqrt{4-r^2}} \frac{zr}{\sqrt{r^2+z^2}} dz dr + \\
 \int_{\theta=0}^{2\pi} \int_{r=1}^2 \int_{z=0}^{\sqrt{4-r^2}} \frac{zr}{\sqrt{r^2+z^2}} dz dr = \\
 2\pi \int_{r=0}^1 r \left[\sqrt{r^2+z^2} \right]_{\sqrt{1-r^2}}^{\sqrt{4-r^2}} dr + 2\pi \int_1^2 r \left[\sqrt{r^2+z^2} \right]_0^{\sqrt{4-r^2}} dr = \\
 2\pi \int_0^1 r (2-1) dr + 2\pi \int_1^2 (2r-r^2) dr = \dots = \frac{7}{3} \pi
 \end{aligned}$$