

Solutions

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Ex. 1 a/ $\underline{p} \in \text{OL}(A) \iff Ax = \underline{p}$ is consistent

So consider:
$$\left[\begin{array}{ccc|c} 1 & 2 & a & 3 \\ -2 & 8 & 2 & -6 \\ 2 & -2 & 1 & 7 \end{array} \right] \begin{array}{l} \downarrow +2 \\ \downarrow -2 \end{array} \sim$$

$$\left[\begin{array}{ccc|c} 1 & 2 & a & 3 \\ 0 & 12 & 2+2a & 0 \\ 0 & -6 & 1-2a & 1 \end{array} \right] \begin{array}{l} \downarrow +\frac{1}{2} R_2 \\ \downarrow \end{array} \sim \left[\begin{array}{ccc|c} 1 & 2 & a & 3 \\ 0 & 12 & 2+2a & 0 \\ 0 & 0 & 2-a & 1 \end{array} \right]$$

This implies: $\underline{p} \in \text{OL}(A) \iff Ax = \underline{p}$ is consistent

$$\iff 2-a \neq 0 \iff a \neq 2$$

b/
$$A \underline{\phi} = \begin{bmatrix} 1 & 2 & a \\ -2 & 8 & 2 \\ 2 & -2 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix} = \begin{bmatrix} 4-2a \\ 0 \\ 0 \end{bmatrix}$$

Using this information: $\underline{\phi} \in \text{NUL}(A)$

$\iff \underline{\phi}$ is a solution of $Ax = \underline{0}$

$$\iff 4-2a = 0 \iff a = 2$$

c/
$$B = \begin{bmatrix} 1 & 2 & b \\ -2 & 4b & 2 \\ b & -2 & 1 \end{bmatrix} \begin{array}{l} \downarrow +2 \\ \downarrow -b \end{array} \sim \begin{bmatrix} 1 & 2 & b \\ 0 & 4b+4 & 2+2b \\ 0 & -2-2b & 1-b^2 \end{bmatrix} \begin{array}{l} \downarrow +\frac{1}{2} \\ \downarrow \end{array}$$

$$\sim \begin{bmatrix} 1 & 2 & b \\ 0 & 4(b+1) & 2(b+1) \\ 0 & 0 & -b^2+b+2 \end{bmatrix}$$

$$\parallel \\ -(b^2-b-2) = -(b-2)(b+1)$$

Now we establish:

if $b \neq 2$ and $b \neq -1$ then $\text{Rank}(B) = 3$

if $b = 2$ then $\text{Rank}(B) = 2$

if $b = -1$ then $\text{Rank}(B) = 1$

(Recall: $\text{Rank}(B) = \text{number of pivot positions of } B$)

Ex. 2

Observe that $H = \text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ and

since $\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is linearly independent

forms $\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ a basis for H .

Let $\underline{x} \in H^\perp \iff \underline{x} \perp \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ and $\underline{x} \perp \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

$$\iff \begin{cases} x_1 + x_2 = 0 \\ x_3 = 0 \end{cases} \iff \underline{x} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \text{ where } x_2 \in \mathbb{R}$$

As a consequence:

$$H^\perp = \text{Span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \right\} \text{ and } \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \right\} \text{ is a basis for } H^\perp$$

Ex. 3

We extend the given two vectors with a third vector \underline{x} such that

$$\underline{x} \perp \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix} \text{ and } \underline{x} \perp \begin{bmatrix} 6 \\ 1 \\ 4 \end{bmatrix}$$

(Note: the vectors $\begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$ and $\begin{bmatrix} 6 \\ 1 \\ 4 \end{bmatrix}$ are orthogonal!)

As a result \underline{x} must satisfy the following linear system:

$$\begin{cases} x_1 + 2x_2 - 2x_3 = 0 \\ 6x_1 + x_2 + 4x_3 = 0 \end{cases}$$

Consider the corresponding augmented matrix:

$$\left[\begin{array}{ccc|c} 1 & 2 & -2 & 0 \\ 6 & 1 & 4 & 0 \end{array} \right] \xrightarrow{-6} \sim \left[\begin{array}{ccc|c} 1 & 2 & -2 & 0 \\ 0 & -11 & 16 & 0 \end{array} \right]$$

Now we find the solutions $\underline{x} = x_3 \begin{bmatrix} -10 \\ 16 \\ 11 \end{bmatrix}$

and e.g. $\begin{bmatrix} -10 \\ 16 \\ 11 \end{bmatrix}$ is an appropriate third vector in order to obtain an orthogonal basis for \mathbb{R}^3 that includes the given two vectors where $x_3 \in \mathbb{R}$

vector in order to obtain an orthogonal basis for \mathbb{R}^3 that includes the given two vectors

Ex. 4

Let $\underline{h} \in H = \text{Span} \{ \underline{v}, \underline{w} \}$,

then we can write $\underline{h} = c_1 \underline{v} + c_2 \underline{w}$ for certain weights $c_1, c_2 \in \mathbb{R}$

$$\text{And } \underline{u} \cdot \underline{h} = \underline{u} \cdot (c_1 \underline{v} + c_2 \underline{w}) = c_1 (\underline{u} \cdot \underline{v}) + c_2 (\underline{u} \cdot \underline{w})$$

$$= c_1 \cdot 0 + c_2 \cdot 0 = 0. \text{ As a result } \underline{u} \perp \underline{h}$$



$\underline{u} \perp \underline{v}$ and $\underline{u} \perp \underline{w}$

Ex. 5 Define $\underline{a}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$, $\underline{a}_2 = \begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix}$ and $\underline{a}_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$,

then $\underline{a}_3 = 2\underline{a}_1 + \underline{a}_2$ and $\{\underline{a}_1, \underline{a}_2\}$ is

linearly independent. So $\{\underline{a}_1, \underline{a}_2\}$ is a

basis for W , but this basis is not orthogonal.

So construct an orthogonal basis for W by using the Gram-Schmidt process.

Take $\underline{b}_1 = \underline{a}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

$$\begin{aligned} \text{and } \underline{b}_2 &= \underline{a}_2 - \left(\frac{\underline{a}_2 \cdot \underline{b}_1}{\underline{b}_1 \cdot \underline{b}_1} \right) \underline{b}_1 = \underline{a}_2 - \left(\frac{-2}{2} \right) \underline{b}_1 \\ &= \underline{a}_2 + \underline{b}_1 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \end{aligned}$$

The component of \underline{v} in W is:

$$\begin{aligned} \underline{w} &= \text{proj}_W \underline{v} = \left(\frac{\underline{v} \cdot \underline{b}_1}{\underline{b}_1 \cdot \underline{b}_1} \right) \underline{b}_1 + \left(\frac{\underline{v} \cdot \underline{b}_2}{\underline{b}_2 \cdot \underline{b}_2} \right) \underline{b}_2 \\ &= \underline{0} + \frac{5}{3} \underline{b}_2 = \begin{bmatrix} 5/3 \\ 5/3 \\ -5/3 \end{bmatrix} \end{aligned}$$

and the component of \underline{v} in W^\perp is

$$\underline{v} - \underline{w} = \begin{bmatrix} -2/3 \\ 4/3 \\ 2/3 \end{bmatrix} = \frac{2}{3} \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$$

Ex 6 a Substituting the data points in the given form yields:

$$\begin{cases} \alpha + \beta = 2 \\ \alpha + \gamma = 3 \\ \alpha + \beta = 3 \\ \alpha + 4\beta - \gamma = 4 \end{cases}$$

OR, in matrix form,

$$A \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = \underline{b} \quad \text{where } A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 4 & -1 \end{bmatrix}$$

$$\text{and } \underline{b} = \begin{bmatrix} 2 \\ 3 \\ 3 \\ 4 \end{bmatrix}$$

$$\text{Compute } A^T A = \begin{bmatrix} 4 & 6 & 0 \\ 6 & 18 & -4 \\ 0 & -4 & 2 \end{bmatrix}$$

$$\text{and } A^T \underline{b} = \begin{bmatrix} 12 \\ 21 \\ -1 \end{bmatrix} \quad \text{and solve } A^T A \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = A^T \underline{b}$$

In order to find the unique least-squares

solution $\begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} 1\frac{1}{2} \\ 1 \\ 1\frac{1}{2} \end{bmatrix}$. So the least-squares

curve has the equation $y = 1\frac{1}{2} + (x-1)^2 + 1\frac{1}{2} \sin\left(\frac{\pi}{2}x\right)$

b/ The corresponding least-squares error is

$$\left\| \underline{b} - A \begin{bmatrix} 1\frac{1}{2} \\ 1 \\ 1\frac{1}{2} \end{bmatrix} \right\| = \left\| \begin{bmatrix} 2 \\ 3 \\ 3 \\ 4 \end{bmatrix} - \begin{bmatrix} 2\frac{1}{2} \\ 3 \\ 2\frac{1}{2} \\ 4 \end{bmatrix} \right\| = \left\| \begin{bmatrix} -\frac{1}{2} \\ 0 \\ \frac{1}{2} \\ 0 \end{bmatrix} \right\|$$

$$= \frac{1}{2} \sqrt{2}$$