

Delft University of Technology, EEMCS faculty Examination Mathematics 2, AESB1210 (test 2) Friday, January 9th, 2015, 13.45-15.45

- It's not allowed to use a calculator or a mathematical table.
- Each answer should be clearly motivated.
- Your grade is obtained by rounding (score+4)/4 to one decimal place.
- Points:

Ex. 1	4	Ex. 2	4	Ex. 3	3	Ex. 4	4	Ex. 5a	2
								Ex. 5b	2
								Ex. 5c	2
Ex. 6	4	Ex. 7	4	Ex. 8	3	Ex. 9	4		

1. Suppose *a*, *b* and *c* are real constants such that *a* is not zero and the system

$$\begin{cases} x_1 + x_2 + x_3 &= f \\ x_1 + (a+1)x_2 + 3x_3 &= g \\ bx_2 + cx_3 &= h \end{cases}$$

is consistent for all possible values of *f*, *g* and *h*. What does this imply for the numbers *a*, *b* and *c*?

2. Find the solutions of the linear system whose augmented matrix is given by

1	-3	0	-1	0	-2	
0	1	0	0	-4	1	and write this solution set in nanametric vector form
0	0	0	1	9	4	and write this solution set in <i>parametric vector form</i> .
0	0	0	0	0	0 _	

- **3.** Let $\underline{a}_1, \underline{a}_2$ and \underline{a}_3 be vectors in \mathbb{R}^n such that $5\underline{a}_2 = 2\underline{a}_1 4\underline{a}_3$ and $A = \begin{bmatrix} \underline{a}_1 & \underline{a}_2 & \underline{a}_3 \end{bmatrix}$, so $\underline{a}_1, \underline{a}_2$ and \underline{a}_3 are the columns of matrix A. Find a solution of the homogeneous linear system $A\underline{x} = \underline{0}$. (Hint: recall the definition of the product of a matrix and a vector)
- **4**. Determine the value(s) of *a* such that $\left\{ \begin{bmatrix} 1 \\ a \end{bmatrix}, \begin{bmatrix} a \\ a+2 \end{bmatrix} \right\}$ is linearly independent.

p.t.o.

- **5.** Let $A = \begin{bmatrix} 1 & -5 & -7 \\ -3 & 7 & 5 \end{bmatrix}$ and let *T* be the corresponding matrix transformation.
 - **a**. Find all vectors \underline{x} that are mapped into $\underline{0}$ by transformation T (so find the null space of T).
 - **b**. Is transformation *T* onto?
 - **c**. Is transformation *T* one-to-one?
- **6**. Let $T : \mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation that first reflects vectors about the x_1x_2 plane and then rotates vectors about the x_2 axis through π radians. Find the standard matrix of *T*.

7. Determine *a* and *d* such that matrix
$$A = \begin{bmatrix} a & 0 \\ 1 & d \end{bmatrix}$$
 has the property $A^2 = A$.
8. Find $x \in \mathbb{R}$ such that $\begin{bmatrix} 2x & 7 \\ 1 & 2 \end{bmatrix}^{-1} = \begin{bmatrix} 2 & -7 \\ -1 & 4 \end{bmatrix}$.

9. Prove or disprove: if A is an 2×2 – matrix such that $A^2 = 0$ then A = 0 (of course by 0 is meant the zero marix with size 2×2).